

# **USER INSTRUCTIONS**

D30 Compact
Digital Positioner

FCD PMENIM0030-04-A5 - 04/21

Installation
Operation
Maintenance





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# 1. Introduction

The D30 is a digital positioner designed primarily for controlling modulating valves. The positioner can be used with single or double acting actuators with either rotary or linear movement.

The D30 can be equipped with modules for limit switches and pressure gauges. Pressure sensors can be installed to offer advanced diagnostics.

The modules can be factory assembled before delivery or fitted later.

The modules for limit switches can contain one of the following:

- · Two mechanical contacts
- · Two proximity switches
- . Two inductive sensors

See page 12 for more options available



Note!

Only authorized technicians are allowed to work with certified products.





# 2. Warning

### Special Conditions for Safe Use

The enclosure of PMV D30(D20) Intrinsically safe version is made of aluminium and any impact or friction caused by external objects shall be avoided in the application. Control Drawing D4-086C contains the parameters for intrinsic safety. The intrinsic safe circuits D30(D20) is insulated from earth and complies with the dielectric strength test of 500 V ac.

### Special Conditions for Safe Use (ATEX/IEC specific)

The surface area of the plastic parts on the cover exceeds the limits specified in EN 60079-0 for II 1G (EPL Ga) for gas group IIC and intensive rubbing or brush charging should be avoided when used in an IIC explosive atmosphere.

The cable connection of the Remote Unit with the D30(D20) unit shall be type A or B in accordance with EN 60079-25. The cable must be adequately mechanically protected in all instances and have a temperature rating for the ambient temperature range at the site.

### Warning!

In a hazardous environment where there is a risk of explosion, electrical connections must comply with the relevant regulations.

Do not disconnect equipment unless area is known to be non-hazardous. or; read, understand and adhere to the manufacturer's live maintenance procedures. To prevent ignition of flammable or combustible atmospheres, disconnect power before servicing,

### Warnings

Substitutions of components may impair suitability for hazardous (classified) locations.

### Environmental requirements

Some switch options may decrease the temperature working range se Control Drawing D4-086C for details. D30(D20) ATEX/ IEC certification temperature range and marking: II 1 G Ex ia IIC T4 Ta -40°C to 85°C Ga.





### Maintenance/service

### Warning!

When upgrading electronically parts inside a PMV positioner approved for installation in Hazardous locations special procedures apply, permission from PMV/Flowserve is required prior to the start of work. Please contact a Flowserve office for information regarding proper procedures.

www.pmv.nu or infopmv@flowserve.com

### Warnina!

Always turn off the air and electrical supplies before starting any work

### General safety

### Safety instruction

Read the safety instructions in this manual carefully before using the product. The installation, operation, and maintenance of the product must be done by staff with the necessary training and experience. If any questions arise during installation, contact the supplier/sales office before continuing work.

### Warning

The valve can open or close very quickly when in operation and, if handled incorrectly, may cause damages to fingers. There may also be unintentional effects due to it fully opening or shutting off the flow in the process pipe. Please note the following:

- If the input signal fails or is switched off, the valve operates quickly to its default position.
- If the compressed air supply fails or is turned off, rapid movements can occur.
- The valve is not controlled by the input signals when in the Out of Service mode. It will open/ close in the event of an internal or external leak.
- If a high value is set for Cut off, fast movements can occur.
- When the valve is controlled in the Manual mode, the valve can operate quickly.
- · Incorrect settings can cause self-oscillation, which can lead to damage.

### *Important*

- Always turn off the compressed air supply before removing or disconnecting the air supply connection or the integral filter.
   Remove or disconnect with care as air connection "C-" is still under pressure even after the air supply is turned off.
- Always work in an ESD (Electrostatic Discharge) protected area when servicing the Printed circuit boards (PCB's). Make sure the
  input signal is switched off.
- The air supply must be free from moisture, water, oil and particles according to DIN/ISO 8573-1-2001 3.2.3



#### **Storage** 3.

### General

The D30(D20) positioner is a precision instrument. Therefore, it is essential that it is handled and stored in the correct way. Always follow the instructions in this IOM!

*Note:* As soon as the positioner is connected and started, internal air venting will provide protection against corrosion and prevent the ingress of moisture. For this reason, the air supply pressure should always be kept on unless repair/maintenance work of the positioner, actuator or valve equipment is in progress.

## Storage indoors

D30 Digital Positioner

Store the positioner in its original packaging. The storage environment must be clean, dry, and cool (15 to 26°C, 59 to 79°F).

Storage outdoors or for a longer period If the positioner must be stored outdoors, it is important that all the cover screws are tightened and that all open ports/connections are properly sealed and/or plugged.

The red shipping plugs are not intended as a permanent outdoor plug. The unit should be packed with a desiccant (silica gel) in a plastic bag or similar, covered with plastic, and not exposed to sunlight, rain, or snow.

# 4. Installation

### Removal of cover

General purpose / Intrinsically safe
Remove cover by first loosening the screw 1 and then the two screws 2.

To install cover, first tighten the screw 1, then the two screws 2.

Tighten to 1.5 Nm  $\pm$  15%.



Supply air should meet requirements specified on <u>page 5</u>. A coalescing filter/regulator should be installed in front of the supply air connection. Now connect the air supply to the filter, which is connected to the D30 positioner.

### **Tubing**

It is recommended to use tubes with a minimum inner diameter of Ø 6 mm (1/4").

### Air supply requirements

D30 Digital Positioner

Poor quality air supply is the main cause of problems in pneumatic systems.

The air supply must be free from moisture, water, oil and particles and delivered @ 1.4-8 barg (20-115 psi)

Standard: *DIN/ISO 8573-1-2001 3.2.3* Filtered to 5 Micron, dew point -40°C/F Oil 1mg/m³ (0,83 ppm by weight)

The air must come from a refrigeration dried supply or be treated in such a way that its dew point is at least 10°C (18°F) below the lowest expected ambient temperature.

To ensure a stable and problem-free air supply, we recommend the installation of a coalescing filter/regulator <5 $\mu$  as close to the positioner as possible.

Before the air supply is connected to the positioner, we recommend the hose is opened freely for 2 to 3 minutes to allow any contamination to be blown out. Direct the air jet into a large paper bag to trap any water, oil, or other foreign materials. If this indicates that the air system is contaminated, it should be properly cleaned before continuing.



*WARNING!* Do not direct the open air jet towards people or objects because it may cause personal injury or damage.



# Mounting

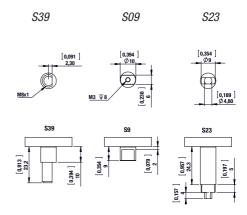
*Note:* If the positioner is installed in a hazardous environment, it must be of a type approved for this purpose.

All versions of the D30 positioner have an ISO F05 footprint. The holes are used to attach the D30 to the mounting bracket B. Please contact PMV or your local distributor representative with actuator specifics for the proper mounting bracket and hardware.

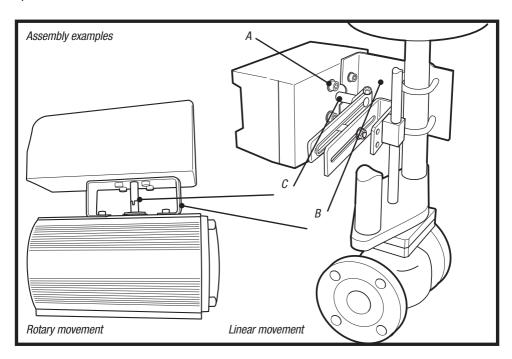
The spindle shaft S09 can be used to suit various actuators in question by the use of adaptors.

It is important that the positioner's spindle shaft and the lever arms, that transfer the actuator movements, are correctly mounted. Any tension between these parts can cause incorrect operation and abnormal wear.

### Spindle shafts



*Note:* There are many spindle options available depending on the actuator. Please contact your local PMV supplier for all options available.





### **Connections**

Air:

Port S Supply air, 1.4-8 barg (20-115 psi)
Port C+ Connection to actuator, opening

Port C- Connection to actuator, opening

(only for double action)

Plug for single action, see below

Dimensions

Air connections: ¼" NPT alt. G ¼"

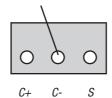
Electrical connection: M20 x 1.5 alt, NPT ½"

Loctite 577 or equivalent is recommended as a sealant.

Electrical connection

See page 12.

Must be plugged when converting to single action function.

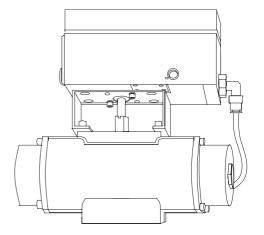


External air Connection

Rotary actuators VDI/VDE 3485 (Namur)
Fit bracket on actuator and secure with 4 x screws.

Mount positioner to bracket. Secure with 4 x M6 screws using 2.5 Nm (1.8 lb ft) torque.

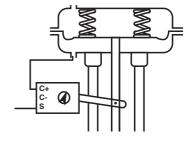
Install tubing between actuator and positioner.





## Single acting positioner, Direct function Actuator with closing spring

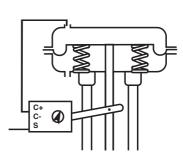
When the control signal increases, the pressure C+ to the actuator is *increased*. The valve stem moves upward and rotates the positioner spindle *counter-clockwise*. When the control signal drops to zero, C+ is vented and the valve closes.



### Reverse function

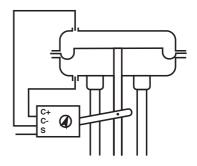
### Actuator with opening spring

When the control signal increases the pressure C+ to the actuator is *increased*. The valve stem moves downward and the positioner spindle rotates *clockwise*. When the control signal drops to zero, C+ is vented and the valve opens.



# Double acting positioner, Direct function Double acting actuator

When the control signal increases, the pressure C+ to the actuator is increased. The valve stem is pressed upward and rotates the positioner spindle counter-clockwise. When the control signal is reduced, the pressure C- to the actuator increases and the valve spindle is pressed downward. If the control signal disappears, the pressure goes to C-, C+ vents, and the valve closes.





# Gauge block

Gauge blocks are available for D30s with  $\frac{1}{4}$ " G or  $\frac{1}{4}$ " NPT air connections. To install, ensure seals are aligned, then use 3 Nm (2.2 lb ft) of torque when fastening the gauge block to the positioner using the two screws supplied with the kit.





### **Electrical connections**

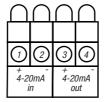
Terminal block diagram for the D30(D20). The terminal block (right) for the positioner is accessible when the aluminium cover is removed. The D30(D20) digital positioner has been designed to operate correctly in electromagnetic (EM) fields found in typical industrial environments. Care should be taken to prevent the positioner from being used in environments with excessively high EM field strengths (greater than 10 V/m). Portable EM devices such as hand-held two-way radios should not be used within 30 cm of the device.

Ensure proper wiring and shielding techniques of the control lines, and route control lines away from electro-magnetic sources that may cause unwanted noise. An electromagnetic line filter can be used to further eliminate noise. In the event of a severe electrostatic discharge near the positioner, the device should be inspected to ensure correct operability. It may be necessary to recalibrate the D30(D20) positioner to restore operation.



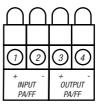
Use a coin to remove the black plug





#### HART and X unit

- 1. Input signal + 4-20mA DC
- 2. Input signal 4-20mA DC
- 4-20mA + Feedback 13-28 VDC
- 4. 4-20mA Feedback 13-28 VDC



Profibus and Fieldbus unit

- 1. Profibus/Fieldbus
- 2. Profibus/Fieldbus
- 3. Profibus/Fieldbus
- 4. Profibus/Fieldbus



D30(D20) optional Switch or remote board

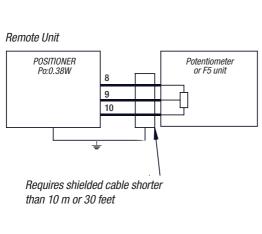
5	6	7	8	9	10)
	Lower Switch			Upper Switch	

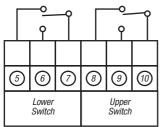


*Warning!* In a hazardous environment where there is a risk of explosion, electrical connections must comply with the relevant regulations.

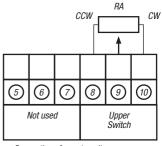


	Switch option	Optional board							
		5	6	7	8	9	10		
Х	No feedback option	na.	na.	na.	na.	na.	na.		
T	4-20 mA transmitter, no switches	na.	na.	na.	na.	na.	na.		
5	Slot type Namur sensor, P+F SJ2-SN	-	+	na.	-	+	na.		
6	Namur V3 type sensor, P&F NJ2-V3-N	-	+	na.	-	+	na.		
7	Slot type Namur sensor, P+F SC2-N0-GN	-	+	na.	-	+	na.		
8	Slot type Namur sensor, P+F SC2-N0-YE	-	+	na.	-	+	na.		
G	Limit switches Mechanical SPDT ,Gold	NC	NO	Com	NC	NO	Com		
N	Namur V3 type sensor, P+F NJ2-V3-N	-	+	na.	-	+	na.		
Р	Limit switches Proximity SPDT	NO	NC	Com	NO	NC	Com		
S	Limit switches Mechanical SPDT	NC	NO	Com	NC	NO	Com		
U	Namur V3 type sensor, P+F NCN4-V3-N0	-	+	na.	-	+	na.		
	Mounting options								
RM	Remote Board (Fedback and switch option =x or T)	na.	na.	na.	ccw	RA	cw		

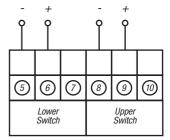




Connection of mechanical and proximity switches



Connection of remote unit

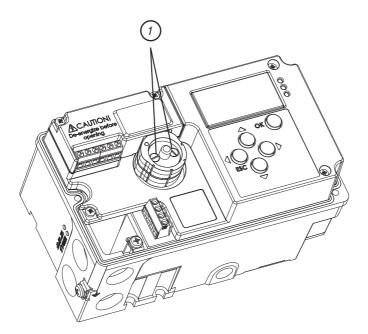


Connection of Namur switch



# Limit switch calibration

- Losen screws (1) and adjust cams.
- Adjust lower cam first and then upper cam
- Tighten screws (1)





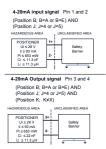
# Feedback option (cont.) Calibration of the 4-20 mA transmitter

Go to menu shown in diagram. Connect mA meter I and check reading. Adjust output signal using Up or Down key until meter I reads 4.00 mA. I Finish by pressing OK. Repeat the above for 20 mA. 4.00 Λ CALIBRATE Expert cal Transm. Transm low Expert cal Transm. Transm low LO= 4,0mA 20.00 Transm. Transm hi  $\bigcirc$ Transm hi HI= 20,0mA

### Connecting switches/input signal/output signal

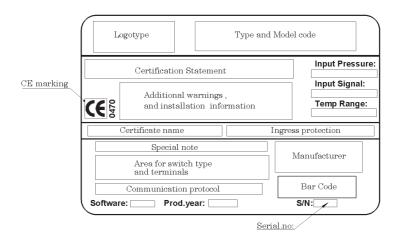
model o	code po	sition K	_							model code position B					E
	Note	SWITCH	Type	CinF	LiuH	UiV	li mA	Pi mW	Min. temp	T4 (*)	T5 (*)	T6 (*)	(IIIC Da)	ATEX ia	IECEx ia
- 5	2	SJ2-SN	NAMUR	30	100	16	25	34	-40	96	68	56	100	Ga ,Da	Ga ,Da
- 6	1	SJ2-N	NAMUR	30	100	16	25	34	-25	96	68	56	100	Ga ,Da	Ga ,Da
7	- 1	SC2-N0-GN	NAMUR	150	150	16	25	34	-25	95	67	55	100	Ga ,Da	Ga ,Da
- 8	- 1	SC2-N0-YE	NAMUR	150	150	16	25	34	-25	95	67	55	100	Ga ,Da	Ga ,Da
G		Mechanical switch gold	Mec.	- 1	1	28	45	315	-40	78	60	45		Ga ,Da	Ga ,Da
N	3	NJ2-V3-N	NAMUR	40	50	16	25	34	-25	96	68	56	100	Ga	Ga
P		Hamlin Proximity	Reed	1	1	28	45	315	-40	80	-			Ga ,Da	Ga ,Da
S		Mechanical switch	Mec.	1	1	28	45	315	-40	78	60	45		Ga ,Da	Ga ,Da
U	3	NCN4-V3-N0	NAMUR	100	100	16	25	34	-25	73	88	100	100	Ga	Ga

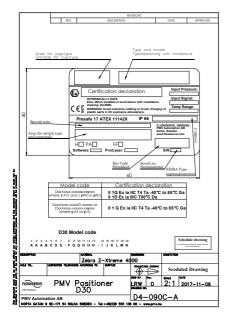
note 1. Higher U, Li and Pi with lower ambient temeratures are allowed see: Certificate PTB 99 ATEX 2219 X or IECEs PTB 11.0091X note 2. Higher U, Li and Pi with lower ambient temeratures are allowed see Certificate PTB 0.1872 2099 X or IECES PTB 11.0092X note 3. Higher U, Li and Pi with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0092X note 3. Higher U, Li and Pi with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0092X note 3. Higher U, Li and Pi with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0092X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temeratures are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X note 3. Higher U, Li and PI with lower ambient temerature are allowed see Certificate PTB 00 ATEX 2003 X or IECES PTB 11.0091X

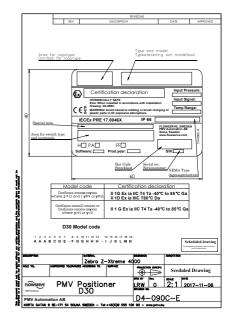




# 5. Type sign example









# 6. D30 Model code

# D30 Digital Positioner model code

<i>A</i> =		Mod D 30		ımbe		11 I C	חים חי	enu, L	ED et	atue													1
В =				s / Ce				Jiiu, L	LD SI	atus													_
		D . A				enera TEX	ıl Pur	pose	versi	on													
		В			IN	IMET	R0																=
		E F			IE Fi	CEX																	1
		N			N	EPSI																	
<i>C</i> =		T Air r	elav		- 11	R CU																	
0 =		Η΄	uiuy		Н	igh Fl	ow S	pool \	/alve														]
D =		Coni G	necti	on Th			oir M	120 v	1 5 0	aatria	ol.												1
		M			1/	4" NI	an, iv PT air	, M20	x 1,5	ectric elect	ai rical												1
_		N	no oti	an 0				, 1/2"	NPT	electr	ical												
E =		2	iecu	on Qi				condu	ıits														1
_		T				Elect	rical	condu	ıits, t	hread	ed Aux. v	rentila	tion										1
F =		Hou:	sing	mate		lumin	um /	Powd	er en	oxi, b	lack												1
G =		Spin	dle /	Мои						,													
		RM 09						unted ne ac	danto	r spin	dle											-	
		21			N	AF Tu	rnex	inclu	ding r	nount	ing bracl												
		23 30									ing kit no een 01/0			3									
		39		,,	IE						cl. moun				ded								
H =		PVA	er / II	ndica		MV. b	lack	cover.	arro	w indi	cator												1
		PVB			Р	MV, b	lack	cover,	no ir	ndicat	or												1
		FWA FWB									w indica ndicator	lor											
<i>l</i> =			pera	ture F			ha 00	oc / 4	005+	. 170	)F\												_
J=		U	t Sin	nal /	_		10 80	°C (-4	U°FI	o 176°	'F)												
0 –		4	t oig	iiui /	4	-20 m																	
		5 P				-20 m rofibu																	
.,		F			F			Fieldb	ous														1
K =		reed X	ibaci	k Opt		o fee	dback	k optio	on														1
		T			4	-20 m	ıA tra	nsmit	ter o		DDT												=
		S N								nical S V3 typ	ie sensoi	, P&F	NJ2-	/3-N									=
		P 5								ty SPI	OT nur senso	or D&F	S 12.	SN									
		6									iur senso												=
L =		Opti 0	ons /	Add-					tion														1
		3						agnos iagno		built	in pressı	ire se	nsors										1
M =			essoi	ies																			_
		X M				o acc auge			G (D/	A 3 ga	uges or S	A 2 g	auges	inclu	ided)								
.,		N			G						gauges o					ed)							
N =		Spec	ciai u	ptior		o spe	cial o	ption	S														1
		S T			E	khaus	st sile	ncers															1
		ΰ				70 de 70 de		Exha	ust s	ilence	rs												j
							,						,							_			_
Α	Α	Α	В	C	D	Ε	-	F	G	G	H H	Н	-	I	J	K	L	M	N				

For latest version of valid model code please see www.pmv.se



# 7. Control

### Menus and pushbuttons

The positioner is controlled using the five pushbuttons and the display, which are accessible when the aluminum cover is removed.

For normal functioning, the display shows the current value. Press the ESC button for two seconds to display the main menu.

Use the pushbuttons to browse through the main menu and the sub-menus.

The main menu is divided up into a basic menu and a full menu, see page 19.

### Other functions

**ESC** 

Exit the menu without making any changes (as long as any changes have not been confirmed with OK).

### **FUNC**

To select function and change parameters.

### 0K

To confirm selection or change of parameters.

### MENU INDICATOR

Displays the position of the current menu row in the menu

### IN SERVICE

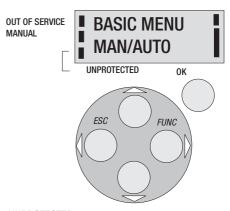
The positioner is following the input signal. This is the normal status when the positioner is working.

### OUT OF SERVICE

The positioner is not following the input signal. Critical parameters can be changed.

### MANUAL

The positioner can be stroked manually using the pushbuttons. See section "Man/Auto", page 25.



### UNPROTECTED

Most of the parameters can be changed when the positioner is in the "Unprotected" position. However, critical parameters are locked when the positioner is in the "In service" position.

LED color (R=Red, Y=Yellow, G=Green)

C	Codes during In Service											
			R	Actual valve position deviates from requested/set position								
			Υ	Fully opened/closed valve using Cut Off (= OK)								
	T		G	Controlling valve position (= OK)								

Со	Codes during Out of service											
	R	Υ	Input signal not calibrated									
	Υ	G	Feedback signal not calibrated									
	Υ	Υ	Out of Service (= 0K)									

Са	Calibration alarm										
	R	G	No feedback movement. Check linkage from actuator to positioner								
	R	Υ	No air available. *(alarm available only when pressure sensors installed)								
R	G	G	No pot connection. Check pot cable inside positioner.								
R	Υ	Υ	No air relay. Check cable inside positioner.								
R	Υ	G	Pot not calibrated. Go to Calibrate->Expert->Pot on LCD menu.								



### Menu indicator

There are indicators at both sides of the display window and they indicate as follows:

Flashing in position Out of service

Flashing in position *Manual* 

Displayed in position Unprotected

The indicators on the right-hand side show the position in the current menu.

### Menus

To display the menus you can select:

- Basic menu, which means you can browse through four different menu items
- Full menu, which comprises ten steps. Use the Shift Menu to browse through the menu items

Full Menu can be locked out using a passcode.

The main menus are shown on the next page and the sub-menus on the subsequent pages.

Changing parameter values

Change by pressing  $\langle \rangle$  until the desired figure is flashing.

Press to step to the desired figure. Confirm by pressing OK.

A change can be undone by pressing the ESC button, which returns you to the previous menu.

■ FULL MENU MAN/AUTO

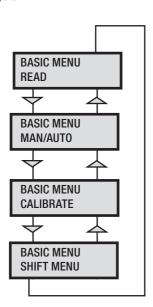
FULL MENU CALIBRATE

FULL MENU
SHIFT MENU

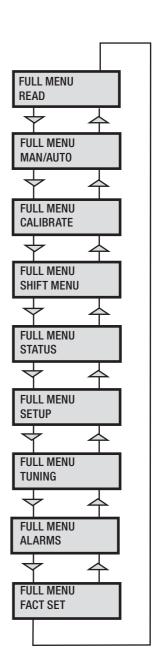


### Basic Menu

Menu system



The menus are described on the following pages.







### First start

"Calibrate" is displayed in the basic menu automatically, the first time power is applied. It can be selected from the basic or full menu at any time.

A complete auto-calibration will take a few minutes depending on size of actuator and includes end limit calibration (zero and span), auto-tuning (dynamically sets the control parameters for the actuated package the positioner is controlling) and a check of the movement speed. Start the automatic calibration by selecting *Auto-Cal* and then answer the questions in the display by pressing *OK* or the respective arrow. More detail about these questions can be found on page 23.

### Calibration error messages

If a fault occurs during calibration, one of the following error messages can be displayed:

### No movement/press ESC to abort

Typically the result of an air delivery issue to the actuator, a stuck valve or actuator, or incorrect mounting and/or linkage arrangement. Check for proper supply air to the positioner, pinched tubing, proper actuator sizing, proper linkage and mounting arrangement.

### Pot uncalibrated/press ESC to abort

The potentiometer is out of range. The potentiomenter is aligned using the Calibrate - Expert cal - pot Menu. The calibration sequence must be restarted after the fault is corrected.

### Tip! Instant quick calibration

The D30 can be instantly calibrated by pressing the top + bottom buttons for 5 seconds (see picture). This function is available from any menu position.

#### First start. Profibus PA

For Profibus PA, connect the input signal at pos 1 and 2 on the terminal block. See Electrical connections in the manual.

In the SETUP/Devicedata/Profibus: change the address from 126 to any number between 1-125. Never use the same number with more than one unit. Install values in failsafe mode, for communication when loss of signal.

Calibrate the unit.

GSD files are available at our web-page www.pmv.nu

To install the D30\_PROFIBUS.DDL file to Siemens SIMATIC PDM.

- 1. Move the files to the directory where the DeviceInstall.exe is located.
- 2. Run DeviceInstall.exe

For Expert Calibration parameters - see page 29!

For further information on calibrating the pot - see <u>page 38</u>



Instant quick calibration

D30 Digital Positioner



Parameter Description SP Setpoint								The SP has 5 bytes, 4 bytes for the float vand one status byte. The status byte need 128 (0x80Hex) or higher for the D30 to ac	ds to be			
RE	ADE	BACK	(	P	ositi	on		The READBACK has 5 bytes, 4 bytes for the float value and one status byte.	ne 4+1=5			
PO	POS_D Digital position							Returns actual position as a digital value definitions as below 0 = Not initialized 1 = Closed 2 = Opened 3 = Intermediate	with 2			
СНЕСКВАСК								Detailed information of the device, coded Several messages can occur at the same				
RCAS_IN Remote Cascade							ascade	The RCAS_IN has 5 bytes, 4 bytes for the float value and one status byte.	4+1=5			
RCAS_OUT Remote Cascade						te Ca	ascade	The RCAS_OUT has 5 bytes, 4 bytes for the float value and one status byte.	4+1=5			
Sta	atus	Byte	: Tab	le								
M	SB						LSB	Meaning D30 info				
0	0	0	0	1	0	Х	X	Not connected				
0	0	0	0	1	1	Х	Х	Device failure PROFIbus PA	A module failure			
0	0	0	1	0	0	Х	Х	Sensor failure No sensor v	alue			
0	0	0	1	1	1	Х	Х	Out of service Al Function	Block in O/S mode			
1	0	0	0	0	0	Х	Х	Good - Non cascade Measured v	alue OK			
								All Alarm va	lues used			
1	0	0	0	0	0	0	0	OK				
1	0	0	0	1	0	0	1	Below low limit Lo Advisory ala	rm			
1	0	0	0	1	0	1	1	Above high limit Hi Advisory ala	rm			
1	0	0	0	1	1	0	1	Lo-Lo Critical aları	n			
1	0	0	0	1	1	1	1	Hi-Hi Critical aları	n			
Ex	amp	le S	P = 4	43.7	<b>'</b> % a	nd 5	0%					
Flo	oat			Н	ex			Status				
43.7 42 2E CC CD						CC (	CD	80				
50.0 42 48 00 00						00 (	00	80				



(FF) Foundation Fieldbus function blocks
Function blocks are sets of data sorted by
function and use. They can be connected to
each other to solve a control process, or to a
controlling DCS. To get a good introduction and
understanding of FF look at www.fieldbus.org
and download the "Technical Overview" from the
About FF pages.

### (TB) Transducer Block

The TB contains unit specific data. Most of the parameters are the same as parameters found on the display. The data and the order of data varies between different products. The AO-block setpoint (SP) and process value (PV) parameters are transceived to the TB through a channel. The TB has to be in AUTO for the AO-block to be in AUTO.

The positioner has to be in menu-auto mode and in service to be controlled from the fieldbus. If the positioner is placed in menu-manual mode then the transducer block will be forced to (LO) local override. In this way a person in the field will be able to control the positioner from the keypad, without collision with a control loop.

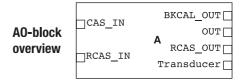
### (RB) Resource Block

The RB is a set of parameters that looks the same for all units and products. The values of the RB define unit information that concerns the Fieldbus Protocol such as MANUFAC\_ID which informs the unique manufacturer id. For Flowserve it is 0x464C53. The RB has to be in AUTO for the AO-block to be in AUTO.

# (AO) Analogue Output Block

The AO follows Fieldbus Foundation's standard on content and action. It is used for transferring (SP) setpoints from the bus to the positioner.

CAS\_IN (cascade input) and RCAS\_IN (remote cascade input) are selected as inputs to the AO block depending on the MODE\_BLK parameter. The selected input will be relayed to the SP parameter of the AO block. BKCAL\_OUT (back calculated output) is a calculated output that



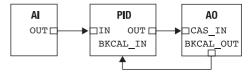
can be sent back to a controlling object so that control bumps can be avoided. Usually the BKCAL\_OUT is set to be the (PV) process value of the AO-block, i.e. the actual measured position of the valve. OUT is the primary calculated output of the AO block. During a limited action (ramping) of the AO block the RCAS\_OUT parameter will supply the final setpoint and the OUT parameter will be the limited output. The transducer block is connected through a channel to the AO block. Through this channel the OUT value and SP are transceived.

In order to set the AO block to AUTO, the TB and the RB have to be in AUTO. Further the AO block has to be scheduled. Using National Instruments Configurator; scheduling can be done by adding the unit to a project and then click on the "upload to device" icon.

To write a setpoint value by hand, add Man to MODE->Permitted parameter, and then choose MODE->Target to Man. Make sure that the unit is scheduled.

# Example

A typical FF block loop control might look like the following: Where the positioner is represented by the AO-block.







The contents of the menu are shown on the next page. The various menu texts are described below.

Auto-Cal Auto-tuning and calibration of end positions

Start tune Starts the tuning. Questions/commands are displayed during

calibration. Select the type of movement, function, etc. with

and confirm with OK as shown in the chart on the next page.

Lose prev value? OK? A warning that the value set previously will be lost (not during the

first auto-tuning).

Direction? Air-to-open. Select for direct function.

Direction? Air-to-close. Select for reverse function.

In service? Press OK Calibration finished. Press OK to start positioner functioning.

(If ESC is pressed, the positioner assumes the "Out of service"

position but the calibration is retained).

TravelCal Calibration of end positions
Start cal Start end position calibration.

Lose prev value? OK? A warning that the previously set value will be lost. Confirm with

OK. The calibration sequence starts.

In service? Press OK Calibration finished. Press OK to start positioner functioning.

(If ESC is pressed, the positioner assumes the "Out of

service"position but the calibration is retained).

Perform Setting gain
Normal 100% gain

Perform G, F, E, D, C, B, A Possibility to select a lower gain in steps.

Default setting is D.

Note. Original P. I. D. will always be shown in display



The menu contents are shown in the figures on the right and the texts are described below:



Current values can be read using the Read Menu and some values can be reset.

Pos Shows current position READ Set&pos Set point and position pos Set&dev Set point and deviation Pos graph Shows position graph Statistics Temp Shows current temperature n cycles READ Statistics set&pos Shows number of cycles. n cycles 1 cycle = [move of valve +change direction+move Statistics opposite direction] regardless acc travel of size of each move/stroke. Acc travel Travel = [accumulated % valve Statistics READ has moved/100]. mean dev set&dev Example: move 60% up + move Statistics 40% down =>Acc travel = 1 m. abs dev READ mean dev Shows accumulated Pos Graph deviation in % Statistics runtime m.abs dev Shows accumulated absolute deviation in % READ Statistics temp # of resets # of resets Shows number of resets **Statistics** runtime Shows accumulated runtime READ since last reset extr. temp Statistics Shows extreme min and max Extr temp **Statistics** temperature histogram READ Shows position and time for Histogram Alarms Statistics position value Reset stat Alarms Displays tripped alarms





The Man/Auto menu is used to change between manual and automatic modes.

The menu contents are shown in the figures on the right and the various texts are described below:

AUT. OK = MAN

Positioner in automatic mode

MAN, OK = AUT

Positioner in manual mode

In the MAN mode, the value of POS can be changed using . The push-buttons increase/decrease the value in steps. The value can also be changed in the same way as for the other parameter values, as described on page 14

### Other functions

C+ can be fully opened by pressing  $\triangle$  and then immediately OK simultaneously.

C- can be fully opened by pressing  $\bigvee$  and OK simultaneously.

C+ and C- can be fully opened for blowing clean by pressing  $\longrightarrow$  and OK simultaneously.



When changing between MAN and AUT mode, the OK button must be pressed for 3 seconds.





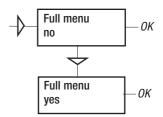
D30 Digital Positioner

The Shift Menu is used to choose between the basic menu and the full menu.

The menu contents are shown in the figures on the right and the various texts are described below:

No Full menu selected.

Basic menu selected. Yes



The Menu can be locked with a passcode, see Setup menu.

### Full Menu



The Status Menu is used to select whether or not the positioner is in service.

The menu contents are shown in the figures on the right and the various texts are described below:

o o service Not in service. Flashing

indicator in upper lefthand corner of display.

in service Positioner in service.

> Critical parameters cannot be changed.

STATUS 0K o o service STATUS 0K in service

When changing between In service and Out of service, the OK button must be pressed for 3 seconds.





The Setup Menu is used for various settings.

The menu contents are shown in the chart on the next page and the various texts are described below:

Actuator	Type of actuator	Size of actuator	Time out
Rotating	Rotating actuator.	Small	10 s
Linear	Linear actuator.	Medium	25 s
		Large	60 s
		Extra large	180 s

Lever Only for linear actuator.

Stroke length to achieve correct display. Input only needed in case display value Lever stroke

is off

Calibration of positions to achieve correct display. Level cal

Direction

Direct function (signal increase opens), Indicator/spindle rotates counter-clock Direct

wise.

Reverse function. Reverse

Character Curves that show position as a function of input signal.

See diagram.

Linear

Equal %

Quick open

Sar root

Custom

Create own curve.

Cust chr

Specify number of points # of point

(3, 5, 9, 17, or 33)

**Cust curve** Enter values on X and Y axes.

Curr range (Use this function to split range)

0% = 4.0 mA

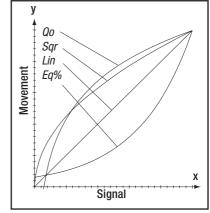
100%=20.0 mA Possibility of selecting which input

signal values will correspond to

0% and 100% movement respectively.

**Examples of settings:** 

4 mA = 0%, 12 mA = 100%, 12 mA = 0%, 20 mA = 100%.



Start in Basic menu or



Start menu TRVL range Settina end positions 0% = 0.0%Select Out of Service. Set percentage value for desired end position (e.g. 3%). Set 0% Select In Service. Connect calibrator. Move forward to desired end position (0%) and press OK. 100%=100.0% Select Out of Service. Set percentage value for desired end position (e.g. 97%). Set 100% Select In Service. Connect calibrator, Move forward to desired end position (100%) and press OK. Tryl ctrl Behavior at set end position Set low Choose between Free (positioner will control until a mechanical top is reached). Limit (stop at set end position), and Cut off (Default value. Go directly to a mechanical stop at a redefined setpoint). Set high Similar to Set low. **Values** Select position for Cut off and Limit at the respective end positions. Passcode Setting passcode for access to the menu

Full menu. Orient Orientation of text on display. Par mode Display of control parameters such as P, I, D or K, Ti, Td. Devicedata HW rew SW rew General parameters. Capability **HART** Menu with HART parameters. Only amendable with HART communicator. It is possible to read from display. Profibus PA Status Indicates present status Device ID Serial number Address 1-126 Tag Allotted ID Descriptor ID description Date SW release date Failsafe Value = preset pos Time = Set time +10sec= time before movement Valve act = failsafe(preset pos) or last value (present pos) Alarm out= 0n/0ff Foundation Fieldbus Serial number Device ID Nod address Address on the bus provided by the DCS system Numbers between 0000 and 9999 can be used TAG-PD TAG Name provided by the DCS system Descriptor D30 positioner Date SW release date Sim iumper Simulate iumper, FF simulation functionality

activated = 0N

**Appearance** On display Language Select menu language. Units Select units. Def. Display Select value(s) to be displayed during service.

as passcodes. 0 = no passcode required.

The display reverts to this value 10 minutes after any change is made.





The menu contents are shown in the chart on the next page and the various texts are described below:

Close time Minimum time from fully open to closed.

Open time Minimum time from closed to fully open.

Deadband Setting deadband. Min. 0.1%.

Expert Advanced settings.

Control See explanations below.

Togglestep Test tool for checking functions. Overlays a square wave on the set value.

Self test Internal test of processor

*Undo* You can read last 20 changes.

### P,I,D and K,Ti,Td parameters

If one of the gains is changed, the corresponding value in the other gain set is changed accordingly.

See diagram below!





The menu contents are shown in the chart on the next page and the various texts are described below:

Deviation Alarm generated when deviation occurs

On/Off Alarm on/off.

Distance Allowed distance before alarm is generated.

Time Total deviation time before alarm is generated.

Alarm out Select ON/OFF offers output on terminals.

Valve act Behavior of valve when alarm is generated.

Limit 1 Alarm above/below a certain level.

On/Off Alarm on/off.

Minipos Setting of desired min. position.

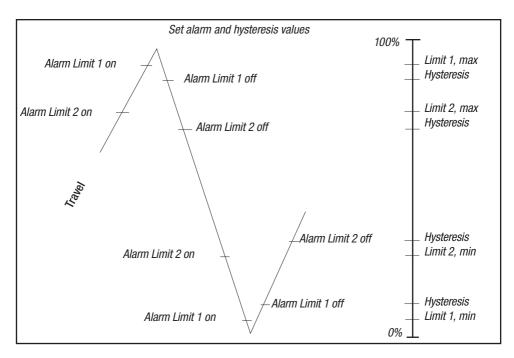
Maxpos Setting of desired max. position.

Hysteresis Desired hysteresis.

Alarm on Select ON/OFF offers output on terminals.

Valve act Behavior of valve when alarm is generated.

Limit 2 See Limit 1.





Temp Alarm based on temperature
On/Off Temperature alarm on/off.
Low temp Temperature setting.
High temp Temperature setting.
Hysteresis Allowed hysteresis.

Alarm out Select ON/OFF offers output on terminals. Valve act Behavior of valve when alarm is generated.

Valve act

No action Alarm generated only. Operations not affected.

Goto open Valve moves to 100%. Positioner changes to position Manual.

Goto close Valve moves to 0%. Positioner changes to position Manual.

Manual Valve stays in unchanged position. Positioner moves to position Manual.



### Expert Calibration

When entering "ExpertCal" mode - walk through the list of parameters described below. Set values where applicable. Confirm by pressing OK.

Set point LO: Use the calibrator set to 4 mA (or set another value on the display). Press OK.

Set point HI: Use a calibrator of 20 mA (or set another value on the display). Press OK.

Pressure LO: Use a supply of 1.4 bar (20 psi) (or set another value on the display). Press OK. Pressure read out only possible on D30 with built in pressure sensor.

Pressure HI: Use a supply of 8 bar (115 psi) (or set another value on the display). Press OK. Pressure read out only possible on D30 with built in pressure sensor.

Transmitter: Connect 10 - 28 VDC. Connect an external mA meter to the loop. Read low value on mA meter and adjust with up/down key. Press OK to set low value.

Repeat procedure to set High value.

Also see video on www.pmv.nu

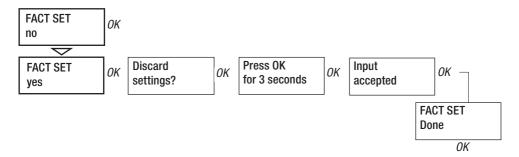
*Pot*: Potentiometer setting, see section 5. Also see video on www.pmv.nu

Full reset: Resets all set values and enters Factory mode. To reset the values only, use FACT SET in main menu, see below.



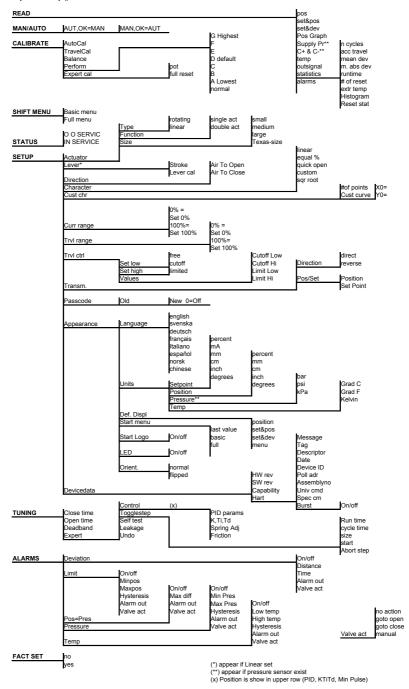
The menu contents are shown in the chart below.

The default values that were set on delivery can be reset using the Fact Set menu. Values from calibration and from other settings will then be lost.





Replacement for page xx in the D30 IOM for software version 1.2





# 8. Maintenance/service

When carrying out service, replacing a circuit board, etc., it may be necessary to remove and refit various parts of the positioner. This is described on the following pages.

Read the Safety Instructions on page 4 and 5 before starting work on the positioner.

Cleanliness is essential when working with the positioner. Contamination in the air ducts will inevitably lead to operational disturbances. Do not disassemble the unit more than that described here.

DO NOT take the valve block apart because its function will be impaired.

When working with the D30 positioner, the work place must be equipped with ESD protection before the work is started.



Always turn off the air and electrical supplies before starting any work.



Please see section for special conditions for safe use and spare parts on page 5!

Please contact a Flowserve office for information regarding proper procedures. www.pmv.nu or infopmv@flowserve.com

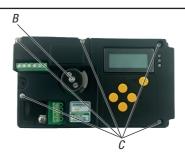
### Disassembling D30

Removing cover and inner cover

- Unscrew the screws A and remove the cover. When mounting cover see page 5.
- Pull off the arrow pointer, B.
- Unscrew the screws C and remove the inner cover.

Note: Removing inner cover will void warranty.





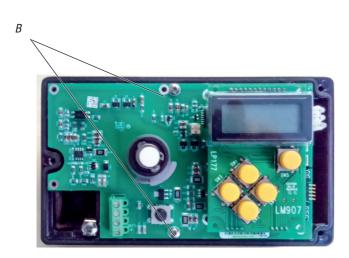


# Circuit boards (PCB)



Disconnect or switch off the electric power supply before starting any work.

- Lift off the display PCB..
- · Release the cable connections.
- Unscrew the two screws B and lift up the circuit board.





### Limit Switches



When installing the switch card, make sure it is placed correctly. Secure the PC board with the two screws. Make sure the holes are centred before tightening the screws.

*Note!* When installing the cam assembly for mechanical switches, retract both switch arms first.

Install the cam assembly and tighten the screws loosely to obtain enough friction to lock the cams.

Adjust the lower cam first, then the upper cam.



### Valve block



Turn off the air and electric power supply before starting any work.

 Remove the three screws A and lift out the valve block

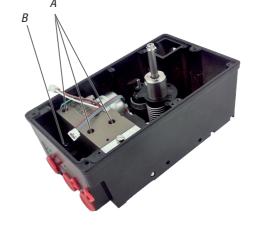
### N.B. Do not disassemble the valve block

 When installing the valve block — torque the three screws to 0,4 Nm and seal with Loctite® 222.



Three pressure sensors are available as an option. They indicate pressure for supply, C- and C+ air, and can be used by ValveSight to enable advanced valve diagnostics.

The sensors are mounted on a circuit board which mounts next to the air relay on the floor of the housing at B using three screws.





Pressure sensor PCB - top view



Pressure sensor PCB - bottom view



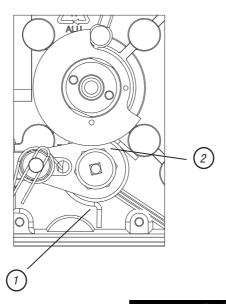
### Potentiometer

90° (270°) spring loaded potentiometer The spring-loaded potentiometer can be removed from the gearwheel for calibration or replacement.

If the potentiometer is replaced or the setting is changed, it must be calibrated.

Select the menu Calibrate - Expert - Cal pot.
 The display shows Set gear.

- Turn the spindle shaft clockwise to end position and press OK. Either turn manually or use the up/down arrows (with supply air) to stroke the positioner to turn the shaft clockwise (see Manual mode page 25).
- Move spring (1) aside and disengage cogwheels. Turn potentiometer according to display until OK is shown. Press OK. See drawing below.
- Move back spring (1) and secure potentiometer (2) calibration. See drawing below.





Potentiometer and cogwheel for 90° rotation



Potentiometer and coawheel for 270° rotation



### 9. Trouble shooting

Symptom	Action
Input signal change to positioner does not affect actuator position.	<ul> <li>Check air supply pressure, air cleanliness, and connection between positioner and actuator.</li> <li>Out of service, in manual mode.</li> <li>Check input signal to positioner.</li> <li>Check mounting and connections of positioner and actuator.</li> </ul>
Change in input signal to positioner makes actuator move to its end position.	Check input signal.     Check mounting and connections of positioner and actuator.
Inaccurate control.	<ul> <li>Perform Auto-calibration and check for any leaks.</li> <li>Uneven air supply pressure.</li> <li>Uneven input signal.</li> <li>Wrong size of actuator being used.</li> <li>High friction in actuator/valve package.</li> <li>Excess play in actuator/valve package.</li> <li>Excess play in mounting of positioner on actuator.</li> <li>Dirty/humid supply air.</li> </ul>
Slow movements, unstable regulation.	<ul> <li>Implement auto-tuning.</li> <li>Increase the deadband (Tuning menu).</li> <li>Adjust Performance (Calibrate menu).</li> </ul>



### 10. Technical data

Rotation angle	min 25° max 100°
Stroke	From 5 mm (0.2")
Input signal	4-20 mA DC
Air supply	1.4-8 barg (20-115 psi) DIN/ISO 8573-1 3.2.3 Free from oil, water and moisture.
Air delivery	Up to 760 nl/min @ 6 bar (29.3 scfm @ 87 psi)
Air consumption	8 nl/min @ 6 bar (0.31 scfm @ 87 psi)
Air connections	1/4" G or NPT
Cable entry	2x M20x1.5 or ½" NPT
Electrical connections	Screw terminals 2.5 mm2 /AWG14
Linearity	<0.4%
Repeatability	<0.5%
Hysteresis	<0.3%
Dead band	0.1-10% adjustable
Display	Graphic, view area 15 x 41 mm (0.6 x 1.6")
UI	5 push buttons
CE directives	93/68EEC, 89/336/EEC, 92 /31/EEC
Voltage drop, w/o HART	8 V
Voltage drop, with HART	9.4 V
Enclosure	IP66
Material	Die-cast Aluminum
Surface treatment	Powder epoxy
Temperature range	-40°C to +80°C (-40°F to 176°F)
Weight	1.8 kg (4 lbs)
Mounting position	Any
Communication protocols	Hart, Profibus PA, Foundation Fieldbus



Mechanical switches	
Туре	SPDT
Size	V3
Rating	3 A/250 VAC / 2 A/30 VDC
Temperature range	-40°C to 80°C (-22°F to 180°F)

NAMUR sensors	
(NJ2-V3-N)	
Туре	Proximity DIN EN 60947-5-6:2000
Load current	1 mA ≤ <i>I</i> ≤ 3 mA
Voltage range	8 VDC
Hysteresis	0.2%
Temperature range	-25°C to 85°C (-13°F to 185°F)
	I

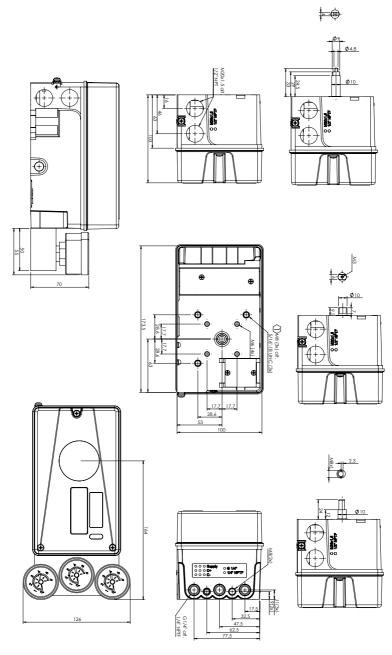
Proximity switches	
Туре	SPDT
Rating	0.4 A @ 24 VDC, Max 10 W
Operating time	Max 1.0 ms
Max voltage	200 VDC
Contact resistance	<b>0.2</b> Ω
Temperature range	-40°C to 80°C (–22°F to 180°F)

Slot NAMUR switches	
(SJ2-SN, SJ2-N)	
Туре	Proximity DIN EN 60947-5-6:2000
Load current	1 mA ≤ <i>I</i> ≤ 3 mA
Voltage	8 VDC
Hysteresis	0.2%
Temperature range	-25°C to 85°C (-40°F to 185°F) SJ2-N -40°C to 85°C (-40°F to 185°F) SJ2-SN

4-20 mA transmitter	
Supply	11-28 VDC
Output	4-20 mA
Resolution	0.1%
Linearity full span	+/-0.5%
Output current limit	30 mA DC
Load impedance	800 Ω @ 24 VDC



### 11. Dimensional Drawing



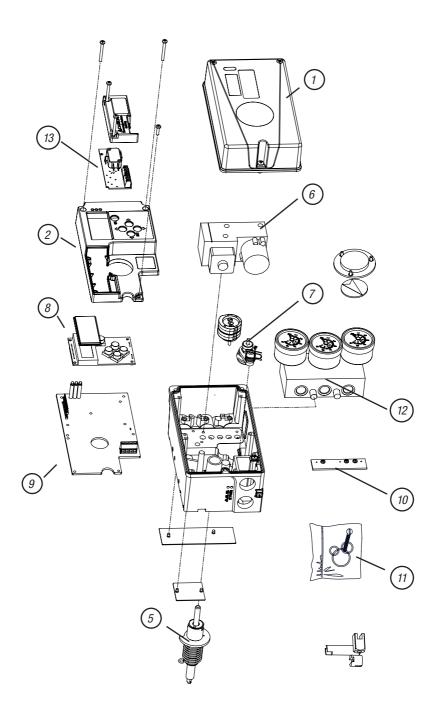


### 12. Spare parts

No	Part no	Description
1	D4-SP37PVA	Black cover incl. screws and flat indicator
1	D4-SP37FWA	White cover incl. screws and flat indicator
2	D4-SP40	Internal cover incl. screws
3	D4-SP1516	External covers SST, 2, incl screws
4	3-SXX	Spindle adaptor (XX = 01, 02, 06, 26, 30, 36)
5	D4-SP05-09	S09 shaft compl. incl. gear wheel, friction clutch, spring
5	D4-SP05-21	S21 shaft compl. incl. gear wheel, friction clutch, spring
5	D4-SP05-23	S23 shaft compl. incl. gear wheel, friction clutch, spring
5	D4-SP05-39	S39 shaft compl. incl. gear wheel, friction clutch, spring
6	D4-SP400	Air relay complete, incl. cable, seal, screws
7	D4-SP08	Potentiometer compl. incl. spring, bracket, cable
8	3-SP37HR	PCB LCD assembly
9	D4-SP7-80H	PCB mother board 4-20 mA / HART
9	D4-SP7-80P	PCB mother board Profibus PA
9	D4-SP7-80F	PCB mother board Fieldbus
10	D4-SP84-3	Pressure sensor assembly complete
11	D4-SPGB	Bag with screws, O-rings, seals, pair of sintered brass silencers, cable gland
12	D4-SP940M	Gauge block G, complete incl. screws, seals, 3 gauges / SST, Brass
12	D4-SP940N	Gauge block G, complete incl. screws, seals, 3 gauges / SST, Brass
13	D4-SP081 S	Limit switches Mechanical SPDT compl.
13	D4-SP081 N	Limit switches Namur V3 P&F NJ2-V3-N compl.
13	D4-SP081 P	Limit switches Proximity SPDT compl.
13	D4-SP081 5	Limit switches Namur slotted P&F SJ2-SN compl.
13	D4-SP081 6	Limit switches Namur slotted P&F SJ2-N compl.

Note: Replacement of certified spare parts require proper qualification and knowledge of applicable standards







### 13. Applied Standards

EN 61000-6-2 C1 2005-09-26

EN 61000-6-3 A2 2007-02-26

EN 61000-6-4 A1 2007-02-26

EN 60204-1 A1 2007-05-21

IEC 61010-1 2010

EN 60079-0 2012+A11:2013

EN 60079-11 2012

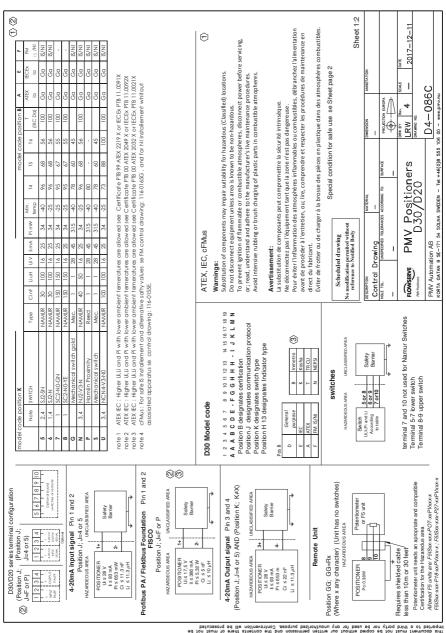
EN 60079-14 2014

EN 60079-26 2015

EN 60079-27 2010

IEC 61158-2 2014

### 14. Control Drawing



## FM only

HAZARDOUS AREA:

Class I,II Division 1 Group A,B,C,D T4 Class I Zone 0,1 AEx ia IIC T4 Class I Division 2 Group A,B,C,DT4 Class I Zone 2 AEx n IICT4 Class III Div 1&2 T4

# INSTALLATION NOTES:

Control equipment connected to the associated apparatus shall not use or generate more than 250Vrms or Vdc. Associated apparatus manufacturer's installations drawing shall be followed when installing this equipment.

Run shielded interconnection cable with shield connected to FM approved associated apparatus ground.

Allows the interconnection of two intrinsically safe devices FM approved with entity parameters not specifically examined in combination as a system when: The intrinsically safety entity concept:

Joor Vocor Vt ⊴ Vmax, loor lscor lt ⊴ Imax, Po ⊴ Pi, Ca or Co ≥ Ci+ Ccable, La or Lo ≥ Li+ Lcable.

# The non-incendive field wiring concept:

Allows the interconnection of non-incendive field wiring apparatus with associated non-incendive field apparatus, Jo or Voc or V1 < Vmax, lo or lsc or It < Imax, Po < Pi, Ca or Co > Ci + Ccable, La or Lo > Li + Lcable. using any of the wiring methods permitted for non-hazardous (unclassified) locations when:

The non-incendive:

Use IS values as general (Vmax = Ui; Imax = Ii) except for folowing

Vmax = 25V. Imax is not regired for this current controlling circut Namur Switch (Pos K=5,6,N or U) Proximity Switch (Pos K=P)

4-20mA input signal (Pin 1 and 2) 4-20mA Output signal Pin 3 and 4 Vmax= 30V, Imax =40mA

Vmax = 30V, Imax = 500mA

Vmax= 30V, Imax is not regired for this current controling circut

# The configurations of associated apparatus shall be FM approved under entity concept. or division 1 installations:

installation of intrinsically safe systems for hazardous (classified) locations" and the Division1 installations should be in accordance with ASI/ISA RP12.06.01 national electrical code (ANSI/NFPA 70).

or division 2 installations:

Using non-incendive field wiring concept, the associated apparatus shall be FM approved under entity concept or non-incendive field wiring concept.

non-incendive field wing concept. If the unit is installed in accordance with the national electrical code (ANSI/NFPA 70) for division 2 wiring methods excluding non-incendive field wiring.

The associated apparatus is not required to be FM approved under entity concept or

LRW LRW LRV LRV 2020-03-10 2019-04-29 2019-09-18 2019-11-19 All cFMus only information added, fench translation warning added Cable dand restriction added. ATEC and IEC FISCO related information added Special conditions for ATEX IEC added G Value change rev 3 revoked CFMus: FISCO added; CFMus: 4:20 mA. Ci value lowered : General; added certification table

modification permited without reference to Notified Body Scheduled drawing

### General requirements for units with 4 conduit openings and NPT threading. Model code position D=N and Position E= 4 or F

4

(Including IEC related Certificates)

Special Conditions for Safe Use

The enclosure of PMV D30(D20) Intrinsically safe version is made of aluminium and any impact or friction caused by external objects shall

be avoided in the application.

Cable glands may not be installed on the same level. the unused openings must be plugged by supplyed A maximum of two cable glands may be used, Cable glands must be used when installing. blanks or other suitable blanks. (se ilustration)



The cable connection of the Remote Unit with the D30(D20) unit shall

be type A or B in accordance with EN 60079-25. The cable must be

temperature rating for the ambient temperature range at the site. adequately mechanically protected in all instances and have a

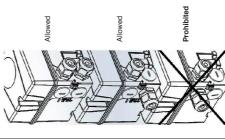
The surface area of the plastic parts on the cover exceeds the limits

The intrinsic safe circuits D30(D20) is insulated from earth and

complies with the dielectric strength test of 500 V ac.

specified in EN 60079-0 for II 1G (EPL Ga) for gas group IIC and intensive rubbing or brush charging should be avoided when used

in an IIC explosive atmosphere.



DESCRIPTION		MATERIAL		DIMENSION		ANNOTATION	
Control Drawing	awing	1		1			
HOLE TOL.	UNSPECIFIED TOLERANDES	ACCORDING TO:	SURFACE	<b>Р</b> ВОЈЕСТІО	PROJECTION EUROPA		
ı	1		1	ф	Δ		
				DRW BY	Rev.	SCALE	DATE
FLOWSERVE	PMV P	sition	ers	LRW	4	ı	2017-12-11
PMV Positioners (	D30/D20	/D20		DRAWING NO.			

Sheet 2:2

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D4-086C





### FCD PMENIM0030-04-A5 - 04/21

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System found at www.flowserve.com

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